

# Protein Structure Tokenizer for Efficient Learning

Hyunkyu Jung<sup>1,3,4</sup> Luiz Felipe Vecchietti<sup>3</sup> Meeyoung Cha<sup>1,3</sup> Ho Min Kim<sup>2,4</sup>

<sup>1</sup>KAIST, School of Computing <sup>2</sup>KAIST, Graduate School of Medical Science and Engineering  
<sup>3</sup>IBS, Data Science Group <sup>4</sup>IBS, Protein Communication Group

{dino8egg}@kaist.ac.kr, {lfelipesv, mcha, kimhm}@ibs.re.kr

## Introduction

High-dimensional data learning:

- Requires Large Memory
- Requires Long Training Time

### Data Tokenization (Data Quantization):

A method that converts high-dimensional data into low-dimensional data.



10	35	42	94
28	2	98	63
36	12	55	77
33	8	65	63

### Image Quantization Example

Here, we propose a **Protein Structure Tokenizer** which enables efficient protein data representation for fast learning with lower memory use.

## Data

### Query on RCSB website (PDB)

- No DNA and RNA structure on pdb file.
- $16 \leq (\# \text{ of polymer residues per deposited model}) \leq 512$
- $16 \leq (\# \text{ of polymer residues per Assembly file}) \leq 512$
- $16 \leq (\text{Polymer Entity Sequence}) \leq 512$

### Remove Assembly Files with given condition

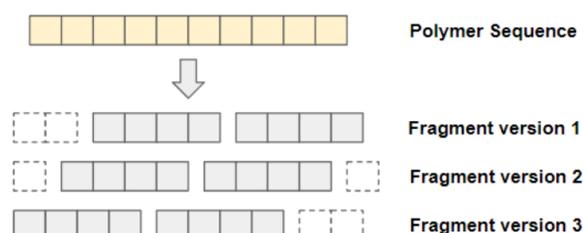
- Assembly files w.o. Ca, C, N, O atoms.
- Assembly files contains amino acid other than basic 20 amino acids.
- Assembly file which is too large. ( $\geq 4096$  Bytes)

→ 65,000 training set, 7,443 testing set

## Methods

### 1. Polymer Fragment Generation

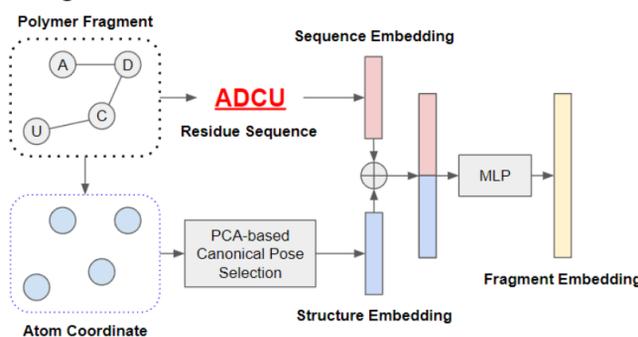
We split the polymer sequence to generate the **polymer fragments** which sequence length set to 4 or 8. For robust representation, we consider all splitting cases.



## Methods

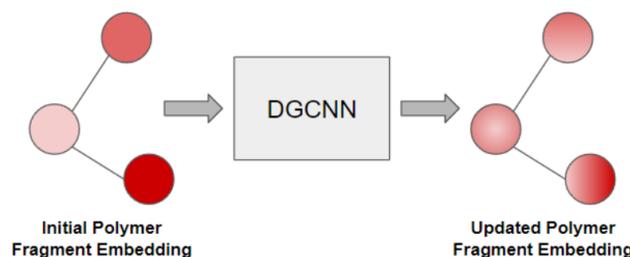
### 2. Intra-Fragment Embedding

We compute an **intra-fragment embedding** by considering both residue sequence and backbone coordinate of a given polymer fragment.

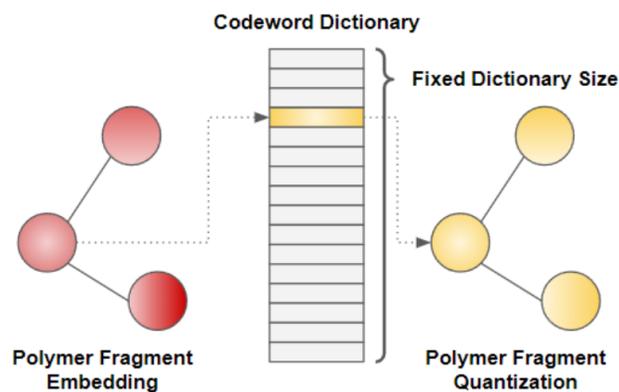


### 3. Inter-Fragment Embedding

We update the polymer fragment embedding by adopting neighbor fragment information using DGCNN network.



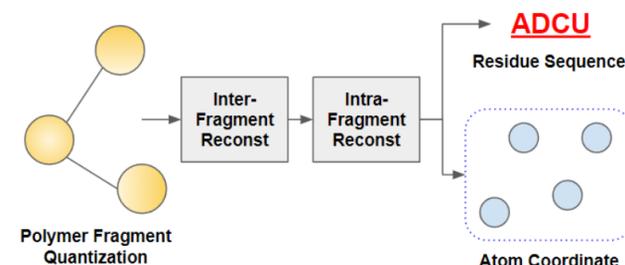
### 4. Codeword Quantization



We tokenize(quantize) a polymer fragment by matching each embedding into fixed a number of cases. We set the dictionary size to 8192.

### 5. Polymer Fragment Reconstruction

For self-supervised learning, we reconstruct the polymer residue and atom coordinate.



## Experiment

### Loss Function

S: Residue Sequence, P: Atom Coordinate

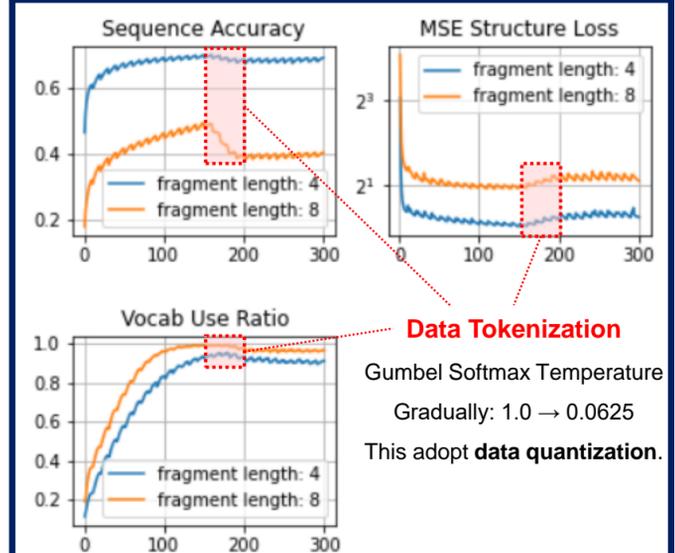
$$\mathcal{L}_{Total} = \mathcal{L}_{type} + \lambda_1 \mathcal{L}_{structure} + \lambda_2 \mathcal{L}_{KL}$$

$$\mathcal{L}_{type} = \mathcal{L}_{CE}(S_j, \hat{S}_j)$$

$$\mathcal{L}_{structure} = \mathcal{L}_{MSE}(P_j, \hat{P}_j)$$

$$\mathcal{L}_{KL} = D_{KL} [Q_\phi(z_j | S_j, P_j), P_\theta(z_j | \tilde{S}_j, \tilde{P}_j)]$$

## Result & Discussion



### Polymer Fragment Training Result

- Both tokenizer use **over 90%** of the Codeword dictionary well.
- The  $Accuracy_{Reconstruct}^{length=4}$  is about **0.7** even  $20^4 > 8192$ .
- The  $Accuracy_{Reconstruct}^{length=8}$  is about **0.4** even  $20^8 \gg 8192$ .
- The MSE Loss of atom coordinate reconstruction **decreased** well.

We introduce **Protein Structure Tokenizer**

- Make **Efficient Representation**
- Enable **Fast Learning**
- Lower Memory Use**
- Similar role as vision tokenizer on ViT

## Reference

- [1] Yu, Xumin, et al. "Point-bert: Pre-training 3d point cloud transformers with masked point modeling." Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition. 2022.
- [2] Ramesh, Aditya, et al. "Zero-shot text-to-image generation." International Conference on Machine Learning. PMLR, 2021.
- [3] Dosovitskiy, Alexey, et al. "An image is worth 16x16 words: Transformers for image recognition at scale." arXiv preprint arXiv:2010.11929 (2020).
- [4] Jang, Eric, Shixiang Gu, and Ben Poole. "Categorical reparameterization with gumbel-softmax." arXiv preprint arXiv:1611.01144 (2016).
- [5] Wang, Yue, et al. "Dynamic graph cnn for learning on point clouds." Acm Transactions On Graphics (tog) 38.5 (2019): 1-12.
- [6] Li, Feiran, et al. "A closer look at rotation-invariant deep point cloud analysis." Proceedings of the IEEE/CVF International Conference on Computer Vision. 2021.

This work was supported by the Institute for Basic Science in South Korea [IBS-R029-C2, IBS-R030-C1].